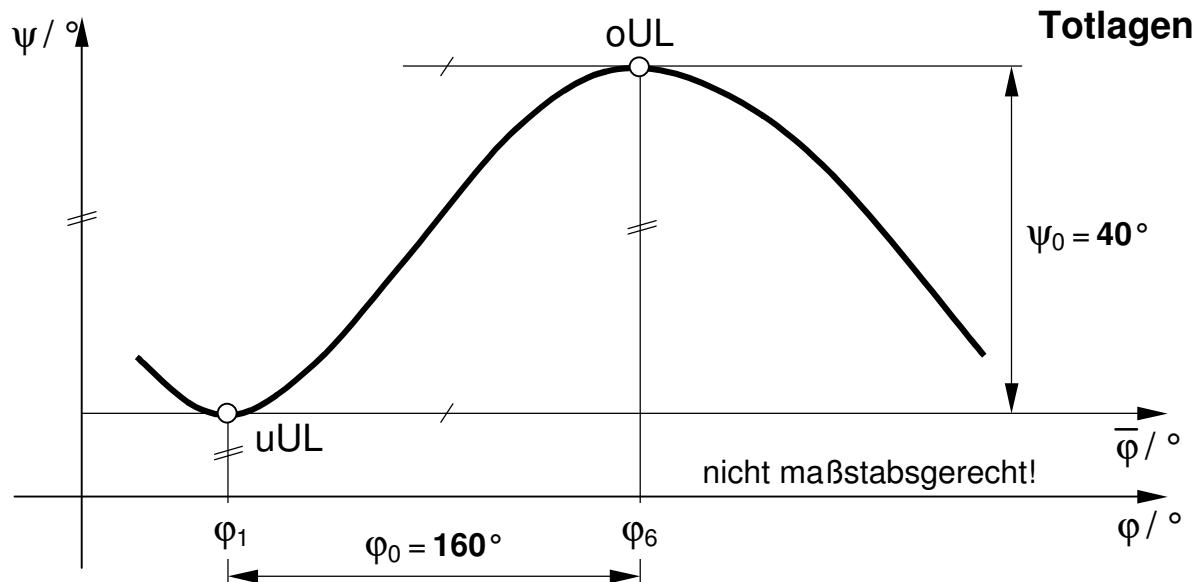


Synthesebeispiel 3



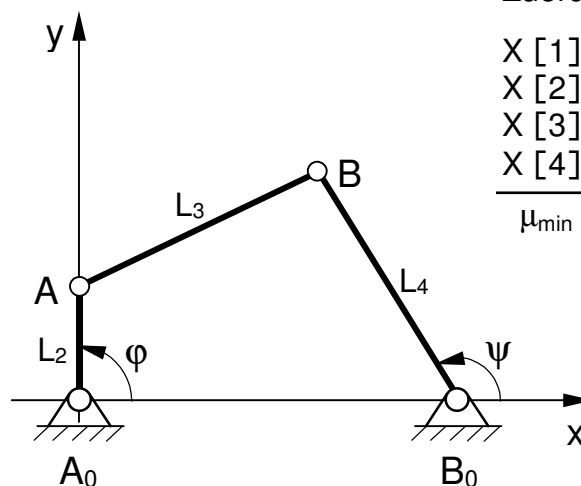
Forderungskatalog

GST	ψ	W_0	$\dot{\psi}$	W_1	$\ddot{\psi}$	W_2	Bemerkungen
1							untere UL
2							ÜF(0) transformiert
3							obere UL
⋮							
10							

Ausgangsgetriebe

Abmessungen nach Schema
Antriebsgrößen

- $\phi_{1,a} = 90^\circ = \phi_{anf}$
- $\phi_{2,a} =$
- $\phi_{3,a} =$
- $\phi_{4,a} =$
- $\phi_{5,a} =$
- $\phi_{6,a} = 250^\circ$
- $\phi_{7,a} =$
- $\phi_{8,a} =$
- $\phi_{9,a} =$
- $\phi_{10,a} =$



Variablenvektor

4-dimensionaler Vektor
Zuordnung

- $X[1] = L_3$
 - $X[2] = L_4$
 - $X[3] = L_2$
 - $X[4] = \phi_{anf}$
- $\mu_{min} \geq 30^\circ$

M = 1 : 2